

# Theoretical Properties

- Structural Operational Semantics
- Correctness of Live Variables Analysis

# The Semantics

A *state* is a mapping from variables to integers:

$$\sigma \in \mathbf{State} = \mathbf{Var} \rightarrow \mathbf{Z}$$

The semantics of arithmetic and boolean expressions

$$\mathcal{A} : \mathbf{AExp} \rightarrow (\mathbf{State} \rightarrow \mathbf{Z}) \quad (\text{no errors allowed})$$

$$\mathcal{B} : \mathbf{BExp} \rightarrow (\mathbf{State} \rightarrow \mathbf{T}) \quad (\text{no errors allowed})$$

The *transitions* of the semantics are of the form

$$\langle S, \sigma \rangle \rightarrow \sigma' \quad \text{and} \quad \langle S, \sigma \rangle \rightarrow \langle S', \sigma' \rangle$$

# Transitions

$$\langle [x := a]^\ell, \sigma \rangle \rightarrow \sigma[x \mapsto \mathcal{A}[[a]]\sigma]$$

$$\langle [\text{skip}]^\ell, \sigma \rangle \rightarrow \sigma$$

$$\frac{\langle S_1, \sigma \rangle \rightarrow \langle S'_1, \sigma' \rangle}{\langle S_1; S_2, \sigma \rangle \rightarrow \langle S'_1; S_2, \sigma' \rangle}$$

$$\frac{\langle S_1, \sigma \rangle \rightarrow \sigma'}{\langle S_1; S_2, \sigma \rangle \rightarrow \langle S_2, \sigma' \rangle}$$

$$\langle \text{if } [b]^\ell \text{ then } S_1 \text{ else } S_2, \sigma \rangle \rightarrow \langle S_1, \sigma \rangle \quad \text{if } \mathcal{B}[[b]]\sigma = \text{true}$$

$$\langle \text{if } [b]^\ell \text{ then } S_1 \text{ else } S_2, \sigma \rangle \rightarrow \langle S_2, \sigma \rangle \quad \text{if } \mathcal{B}[[b]]\sigma = \text{false}$$

$$\langle \text{while } [b]^\ell \text{ do } S, \sigma \rangle \rightarrow \langle (S; \text{while } [b]^\ell \text{ do } S), \sigma \rangle \quad \text{if } \mathcal{B}[[b]]\sigma = \text{true}$$

$$\langle \text{while } [b]^\ell \text{ do } S, \sigma \rangle \rightarrow \sigma \quad \text{if } \mathcal{B}[[b]]\sigma = \text{false}$$

## Example:

$\langle [y:=x]^1; [z:=1]^2; \text{while } [y>1]^3 \text{ do } ([z:=z*y]^4; [y:=y-1]^5); [y:=0]^6, \sigma_{300} \rangle$   
→  $\langle [z:=1]^2; \text{while } [y>1]^3 \text{ do } ([z:=z*y]^4; [y:=y-1]^5); [y:=0]^6, \sigma_{330} \rangle$   
→  $\langle \text{while } [y>1]^3 \text{ do } ([z:=z*y]^4; [y:=y-1]^5); [y:=0]^6, \sigma_{331} \rangle$   
→  $\langle [z:=z*y]^4; [y:=y-1]^5;$   
     $\text{while } [y>1]^3 \text{ do } ([z:=z*y]^4; [y:=y-1]^5); [y:=0]^6, \sigma_{331} \rangle$   
→  $\langle [y:=y-1]^5; \text{while } [y>1]^3 \text{ do } ([z:=z*y]^4; [y:=y-1]^5); [y:=0]^6, \sigma_{333} \rangle$   
→  $\langle \text{while } [y>1]^3 \text{ do } ([z:=z*y]^4; [y:=y-1]^5); [y:=0]^6, \sigma_{323} \rangle$   
→  $\langle [z:=z*y]^4; [y:=y-1]^5;$   
     $\text{while } [y>1]^3 \text{ do } ([z:=z*y]^4; [y:=y-1]^5); [y:=0]^6, \sigma_{323} \rangle$   
→  $\langle [y:=y-1]^5; \text{while } [y>1]^3 \text{ do } ([z:=z*y]^4; [y:=y-1]^5); [y:=0]^6, \sigma_{326} \rangle$   
→  $\langle \text{while } [y>1]^3 \text{ do } ([z:=z*y]^4; [y:=y-1]^5); [y:=0]^6, \sigma_{316} \rangle$   
→  $\langle [y:=0]^6, \sigma_{316} \rangle$   
→  $\sigma_{306}$

# Equations and Constraints

Equation system  $LV^=(S_*)$ :

$$LV_{exit}(\ell) \quad \equiv \quad \begin{cases} \emptyset & \text{if } \ell \in \mathit{final}(S_*) \\ \bigcup \{LV_{entry}(\ell') \mid (\ell', \ell) \in \mathit{flow}^R(S_*)\} & \text{otherwise} \end{cases}$$

$$LV_{entry}(\ell) \quad \equiv \quad (LV_{exit}(\ell) \setminus \mathit{kill}_{LV}(B^\ell)) \cup \mathit{gen}_{LV}(B^\ell)$$

where  $B^\ell \in \mathit{blocks}(S_*)$

Constraint system  $LV^\subseteq(S_*)$ :

$$LV_{exit}(\ell) \quad \supseteq \quad \begin{cases} \emptyset & \text{if } \ell \in \mathit{final}(S_*) \\ \bigcup \{LV_{entry}(\ell') \mid (\ell', \ell) \in \mathit{flow}^R(S_*)\} & \text{otherwise} \end{cases}$$

$$LV_{entry}(\ell) \quad \supseteq \quad (LV_{exit}(\ell) \setminus \mathit{kill}_{LV}(B^\ell)) \cup \mathit{gen}_{LV}(B^\ell)$$

where  $B^\ell \in \mathit{blocks}(S_*)$

## Lemma

Each solution to the equation system  $LV^=(S_*)$  is also a solution to the constraint system  $LV^⊆(S_*)$ .

**Proof:** Trivial.

## Lemma

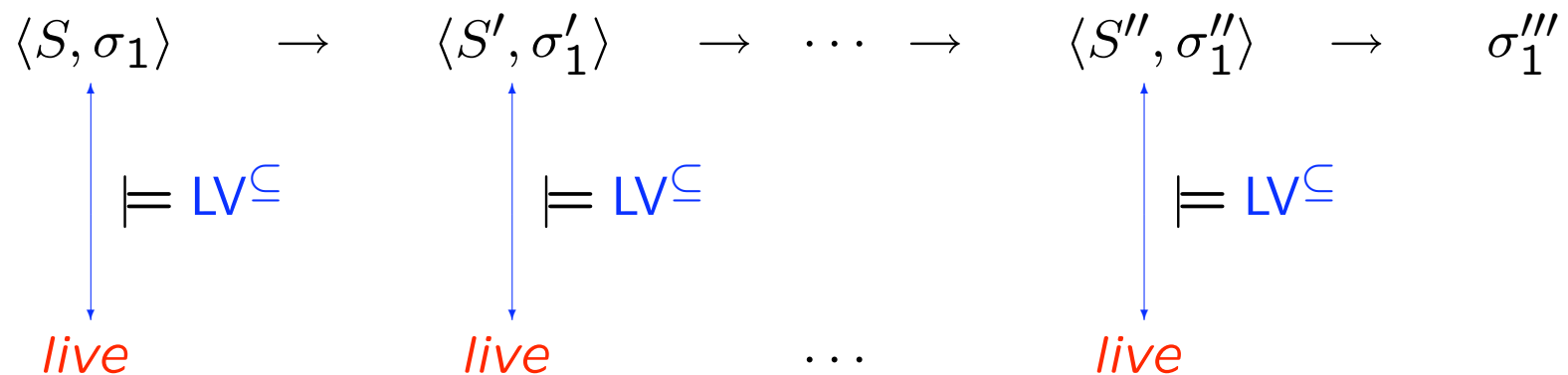
The **least** solution to the equation system  $LV^=(S_*)$  is also the **least** solution to the constraint system  $LV^⊆(S_*)$ .

**Proof:** Use Tarski's Theorem.

**Naive Proof:** Proceed by contradiction. Suppose some LHS is strictly greater than the RHS. Replace the LHS by the RHS in the solution. Argue that you still have a solution. This establishes the desired contradiction.

## Lemma

A solution *live* to the constraint system is preserved during computation



**Proof:** requires a lot of machinery — see the book.

# Correctness Relation

$$\sigma_1 \sim_V \sigma_2$$

means that for all practical purposes the two states  $\sigma_1$  and  $\sigma_2$  are equal: only the values of the live variables of  $V$  matters and here the two states are equal.

## Example:

Consider the statement  $[x:=y+z]^\ell$

Let  $V_1 = \{y, z\}$ . Then  $\sigma_1 \sim_{V_1} \sigma_2$  means  $\sigma_1(y) = \sigma_2(y) \wedge \sigma_1(z) = \sigma_2(z)$

Let  $V_2 = \{x\}$ . Then  $\sigma_1 \sim_{V_2} \sigma_2$  means  $\sigma_1(x) = \sigma_2(x)$



# Correctness Theorem

The relation “ $\sim$ ” is *invariant* under computation: the live variables for the initial configuration remain live throughout the computation.

